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Common coupled fixed point theorems for θ - ψ -contraction mappings endowed with a directed graph

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Abstract

In this paper, we present some existence and uniqueness results for coupled coincidence point and common fixed point of θ - ψ -contraction mappings in complete metric spaces endowed with a directed graph. Our results generalize the results obtained by Kadelburg *et al.* (Fixed Point Theory Appl. 2015:27, 2015, doi:10.1007/s11590-013-0708-4). We also have an application to some integral system to support the results.

MSC: coupled fixed point; coupled coincidence point; common fixed point; Geraghty-type condition; edge preserving; metric spaces; connected graph; monotone; partially ordered set

1 Introduction and preliminaries

For $F : X \times X \rightarrow X$ and $g : X \rightarrow X$, a concept of coupled coincidence point $(x, y) \in X \times X$ such that $gx = F(x, y)$ and $gy = F(y, x)$ was first introduced by Lakshimikantham and Ćirić [2]. Their results extended the result in [3, 4]. Also, the existence and uniqueness of a coupled coincidence point for such a mapping that satisfies the mixed monotone property in a partially ordered metric space were studied. Consequently, a number of coupled fixed point and coupled coincidence point results have been shown recently. For example, see [5–17].

Choudhury and Kundu [7] give a notion of compatibility.

Definition 1.1 ([7]) Let (X, d) be a metric space, and let $g : X \rightarrow X$ and $F : X \times X \rightarrow X$. The mappings g and F are said to be *compatible* if

$$\lim_{n \rightarrow \infty} d(gF(x_n, y_n), F(gx_n, gy_n)) = 0 \quad \text{and} \quad \lim_{n \rightarrow \infty} d(gF(y_n, x_n), F(gy_n, gx_n)) = 0$$

whenever $\{x_n\}$ and $\{y_n\}$ are sequences in X such that $\lim_{n \rightarrow \infty} F(x_n, y_n) = \lim_{n \rightarrow \infty} gx_n$ and $\lim_{n \rightarrow \infty} F(y_n, x_n) = \lim_{n \rightarrow \infty} gy_n$.

Let Θ denote the class of all functions $\theta : [0, \infty) \times [0, \infty) \rightarrow [0, 1)$ that satisfy the following conditions:

$$(\theta_1) \quad \theta(s, t) = \theta(t, s) \text{ for all } s, t \in [0, \infty);$$

(θ_2) for any two sequences $\{s_n\}$ and $\{t_n\}$ of nonnegative real numbers,

$$\theta(s_n, t_n) \rightarrow 1 \implies s_n, t_n \rightarrow 0.$$

In 2015, Kadelburg *et al.* [1] used the monotone and g -monotone properties to obtain common coupled fixed point theorems for Geraghty-type contraction with compatibility of F and g .

Let (X, d) be a metric space, Δ be a diagonal of $X \times X$, and G be a directed graph with no parallel edges such that the set $V(G)$ of its vertices coincides with X and $\Delta \subseteq E(G)$, where $E(G)$ is the set of the edges of the graph. That is, G is determined by $(V(G), E(G))$. We will use this notation of G throughout this work.

The fixed point theorem using the context of metric spaces endowed with a graph was first studied by Jachymski [18]. The result generalized the Banach contraction principle to mappings on metric spaces with a graph. Since then, many authors studied the problem of existence of fixed points for single-valued mappings and multivalued mappings in several spaces with graphs; see [19–23].

Recently, Chifu and Petrusel [24] give the concept of G -continuity for a mapping $F : X^2 \rightarrow X$ and the property A as follows.

Definition 1.2 Let (X, d) be a complete metric space, G be a directed graph, and $F : X^2 \rightarrow X$ be a mapping. Then

- (i) F is called G -continuous if for all $(x^*, y^*) \in X^2$ and for any sequence $(n_i); i \in \mathbb{N}$ of positive integers such that $F(x_{n_i}, y_{n_i}) \rightarrow x^*, F(y_{n_i}, x_{n_i}) \rightarrow y^*$ as $i \rightarrow \infty$ and $(F(x_{n_i}, y_{n_i}), F(x_{n_i+1}, y_{n_i+1})), (F(y_{n_i}, x_{n_i}), F(y_{n_i+1}, x_{n_i+1})) \in E(G)$, we have that

$$F(F(x_{n_i}, y_{n_i}), F(y_{n_i}, x_{n_i})) \rightarrow F(x^*, y^*) \quad \text{and}$$

$$F(F(y_{n_i}, x_{n_i}), F(x_{n_i}, y_{n_i})) \rightarrow F(y^*, x^*) \quad \text{as } i \rightarrow \infty;$$

- (ii) (X, d, G) has property A if for any sequence $(x_n)_{n \in \mathbb{N}} \subset X$ with $x_n \rightarrow x$ as $n \rightarrow \infty$ and $(x_n, x_{n+1}) \in E(G)$ for $n \in \mathbb{N}$, then $(x_n, x) \in E(G)$.

Their results generalized the result in [4] by using the context of metric spaces endowed with a directed graph.

The aim of this work is to prove some existence and uniqueness results for a coupled coincidence point and a common fixed point of θ - ψ contraction mappings in complete metric spaces endowed with a directed graph. The results generalize the results obtained by Kadelburg *et al.* [1]. An application to some integral system is provided to support the results.

2 Common coupled fixed point

We define the set $CcFix(F)$ of all coupled coincidence points of mappings $F : X^2 \rightarrow X$ and $g : X \rightarrow X$ and the set $(X^2)_g^F$ as follows:

$$CcFix(F) = \{(x, y) \in X^2 : F(x, y) = gx \text{ and } F(y, x) = gy\}$$

and

$$(X^2)_g^F = \{(x, y) \in X^2 : (gx, F(x, y)), (gy, F(y, x)) \in E(G)\}.$$

Now, we give some definitions that are useful for our main results.

Definition 2.1 We say that $F : X^2 \rightarrow X$ and $g : X \rightarrow X$ are G -edge preserving if

$$[(gx, gu), (gy, gv) \in E(G)] \Rightarrow [(F(x, y), F(u, v)), (F(y, x), F(v, u)) \in E(G)].$$

Definition 2.2 Let (X, d) be a complete metric space, and $E(G)$ be the set of the edges of the graph. We say that $E(G)$ satisfies the transitivity property if and only if, for all $x, y, a \in X$,

$$(x, a), (a, y) \in E(G) \rightarrow (x, y) \in E(G).$$

Let Ψ denote the class of all functions $\psi : [0, \infty) \rightarrow [0, \infty)$ that satisfy the following conditions:

- (ψ_1) ψ is nondecreasing;
- (ψ_2) $\psi(s + t) \leq \psi(s) + \psi(t)$;
- (ψ_3) ψ is continuous;
- (ψ_4) $\psi(t) = 0 \Leftrightarrow t = 0$.

Definition 2.3 Let (X, d) be a complete metric space endowed with a directed graph G . The mappings $F : X^2 \rightarrow X$ and $g : X \rightarrow X$ are called a θ - ψ -contraction if:

- (1) F and g is G -edge preserving;
- (2) there exist $\theta \in \Theta$ and $\psi \in \Psi$ such that for all $x, y, u, v \in X$ satisfying $(gx, gu), (gy, gv) \in E(G)$,

$$\psi(d(F(x, y), F(u, v))) \leq \theta(d(gx, gu), d(gy, gv))\psi(M(gx, gu, gy, gv)), \tag{1}$$

where $M(gx, gu, gy, gv) = \max\{d(gx, gu), d(gy, gv)\}$.

Lemma 2.4 Let (X, d) be a complete metric space endowed with a directed graph G , and let $F : X^2 \rightarrow X$ and $g : X \rightarrow X$ be a θ - ψ -contraction. Assume that there exist $x_0, y_0, a_0, b_0 \in X$ and $F(X \times X) \subset g(X)$. Then:

- (i) There exists sequences $\{x_n\}, \{y_n\}, \{a_n\}, \{b_n\}$ in X for which

$$\begin{aligned} gx_n &= F(x_{n-1}, y_{n-1}) \quad \text{and} \quad gy_n = F(y_{n-1}, x_{n-1}), \\ ga_n &= F(a_{n-1}, b_{n-1}) \quad \text{and} \quad gb_n = F(b_{n-1}, a_{n-1}) \quad \text{for } n = 1, 2, \dots \end{aligned} \tag{2}$$

- (ii) If (gx_n, ga_n) and $(gy_n, gb_n) \in E(G)$ for all $n \in \mathbb{N}$, then

$$\lim_{n \rightarrow \infty} d_n = \lim_{n \rightarrow \infty} M(gx_n, ga_n, gy_n, gb_n) = 0.$$

Proof (i) Let $x_0, y_0, a_0, b_0 \in X$. By the assumption that $F(X \times X) \subset g(X)$ and $F(x_0, y_0), F(y_0, x_0), F(a_0, b_0), F(b_0, a_0) \in X$, it easy to construct sequences $\{x_n\}, \{y_n\}, \{a_n\}$, and $\{b_n\}$ in X for which

$$\begin{aligned} gx_n &= F(x_{n-1}, y_{n-1}) \quad \text{and} \quad gy_n = F(y_{n-1}, x_{n-1}), \\ ga_n &= F(a_{n-1}, b_{n-1}) \quad \text{and} \quad gb_n = F(b_{n-1}, a_{n-1}) \quad \text{for } n = 1, 2, \dots \end{aligned}$$

(ii) Let (gx_n, ga_n) and $(gy_n, gb_n) \in E(G)$ for all $n \in \mathbb{N}$. Using the θ - ψ -contraction (1) and (2), we obtain that

$$\begin{aligned} \psi(d(gx_{n+1}, ga_{n+1})) &= \psi(d(F(x_n, y_n), F(a_n, b_n))) \\ &\leq \theta(d(gx_n, ga_n), d(gy_n, gb_n))\psi(M(gx_n, ga_n, gy_n, gb_n)) \end{aligned} \tag{3}$$

and

$$\begin{aligned} \psi(d(gy_{n+1}, gb_{n+1})) &= \psi(d(F(y_n, x_n), F(b_n, a_n))) \\ &\leq \theta(d(gy_n, gb_n), d(gx_n, ga_n))\psi(M(gy_n, gb_n, gx_n, ga_n)) \\ &= \theta(d(gx_n, ga_n), d(gy_n, gb_n))\psi(M(gx_n, ga_n, gy_n, gb_n)) \end{aligned} \tag{4}$$

for all $n \in \mathbb{N}$. From (3) and (4) we get

$$\begin{aligned} &\psi(M(gx_{n+1}, ga_{n+1}, gy_{n+1}, gb_{n+1})) \\ &= \psi(\max\{d(gx_{n+1}, ga_{n+1}), d(gy_{n+1}, gb_{n+1})\}) \\ &\leq \theta(d(gx_n, ga_n), d(gy_n, gb_n))\psi(M(gx_n, ga_n, gy_n, gb_n)) \\ &< \psi(M(gx_n, ga_n, gy_n, gb_n)) \end{aligned} \tag{5}$$

for all $n \in \mathbb{N}$, that is,

$$\psi(M(gx_{n+1}, ga_{n+1}, gy_{n+1}, gb_{n+1})) < \psi(M(gx_n, ga_n, gy_n, gb_n)).$$

Regarding the properties of ψ , we conclude that

$$M(gx_{n+1}, ga_{n+1}, gy_{n+1}, gb_{n+1}) < M(gx_n, ga_n, gy_n, gb_n).$$

It follows that $d_n := M(gx_n, ga_n, gy_n, gb_n)$ is decreasing. Then $d_n \rightarrow d$ as $n \rightarrow \infty$ for some $d \geq 0$. We claim that $d = 0$. Suppose not. Using (5), we have

$$\frac{\psi(M(gx_{n+1}, ga_{n+1}, gy_{n+1}, gb_{n+1}))}{\psi(M(gx_n, ga_n, gy_n, gb_n))} \leq \theta(d(gx_n, ga_n), d(gy_n, gb_n)) < 1.$$

Taking the limit as $n \rightarrow \infty$, we have

$$\theta(d(gx_n, ga_n), d(gy_n, gb_n)) \rightarrow 1.$$

Since $\theta \in \Theta$,

$$d(gx_n, ga_n) \rightarrow 0 \quad \text{and} \quad d(gy_n, gb_n) \rightarrow 0$$

as $n \rightarrow \infty$. Therefore,

$$\lim_{n \rightarrow \infty} d_n = \lim_{n \rightarrow \infty} M(gx_n, ga_n, gy_n, gb_n) = 0,$$

which is a contradiction. Hence,

$$\lim_{n \rightarrow \infty} d_n = \lim_{n \rightarrow \infty} M(gx_n, ga_n, gy_n, gb_n) = 0 \quad \square$$

Next, we will prove the main result.

Theorem 2.5 *Let (X, d) be a complete metric space endowed with a directed graph G , and let $F : X^2 \rightarrow X$ and $g : X \rightarrow X$ be a θ - ψ -contraction. Suppose that:*

- (i) g is continuous, and $g(X)$ is closed;
- (ii) $F(X \times X) \subset g(X)$, and g and F are compatible;
- (iii) F is G -continuous, or the tripled (X, d, G) has property A ;
- (iv) $E(G)$ satisfies the transitivity property.

Under these conditions, $CcFix(F) \neq \emptyset$ if and only if $(X^2)_g^F \neq \emptyset$.

Proof Let $CcFix(F) \neq \emptyset$. Then there exists $(u, v) \in CcFix(F)$ such that $(gu, F(u, v)) = (gu, gu)$ and $(gv, F(v, u)) = (gv, gv) \in \Delta \subset E(G)$. Thus, $(gu, F(u, v))$ and $(gv, F(v, u)) \in E(G)$. It follows that $(u, v) \in (X^2)_g^F$, so that $(X^2)_g^F \neq \emptyset$.

Now, suppose that $(X^2)_g^F \neq \emptyset$. Let $x_0, y_0 \in X$ be such that $(x_0, y_0) \in (X^2)_g^F$. Then $(gx_0, F(x_0, y_0))$ and $(gy_0, F(y_0, x_0)) \in E(G)$. From Lemma 2.4(i) we have sequences $\{x_n\}$ and $\{y_n\}$ in X for which

$$gx_n = F(x_{n-1}, y_{n-1}) \quad \text{and} \quad gy_n = F(y_{n-1}, x_{n-1}) \quad \text{for } n = 1, 2, \dots$$

Since $(gx_0, F(x_0, y_0)) = (gx_0, gx_1)$ and $(gy_0, F(y_0, x_0)) = (gy_0, gy_1) \in E(G)$ and F and g are G -edge preserving, we have $(F(x_0, y_0), F(x_1, y_1)) = (gx_1, gx_2)$ and $(F(y_0, x_0), F(y_1, x_1)) = (gy_1, gy_2) \in E(G)$. By induction we shall obtain (gx_{n-1}, gx_n) and $(gy_{n-1}, gy_n) \in E(G)$ for each $n \in \mathbb{N}$. By Lemma 2.4(ii) we have

$$d_n := M(gx_{n-1}, gx_n, gy_{n-1}, gy_n) \rightarrow 0 \quad \text{as } n \rightarrow \infty. \tag{6}$$

Now, we shall show that $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequences. Applying a similar argument as in the proof of Theorem 3.1 in [1] and using (6), condition (iv), and property of ψ , it follows that $\{gx_n\}$ and $\{gy_n\}$ are Cauchy sequences. By condition (i) there exist $u, v \in g(X)$ such that

$$\lim_{n \rightarrow \infty} gx_n = \lim_{n \rightarrow \infty} F(x_n, y_n) = u \quad \text{and} \quad \lim_{n \rightarrow \infty} gy_n = \lim_{n \rightarrow \infty} F(y_n, x_n) = v.$$

By the compatibility of g and F we have that

$$\lim_{n \rightarrow \infty} d(gF(x_n, y_n), F(gx_n, gy_n)) = 0 \quad \text{and} \quad \lim_{n \rightarrow \infty} d(gF(y_n, x_n), F(gy_n, gx_n)) = 0. \tag{7}$$

Now, suppose that (a) F is G -continuous. It is easy to see that

$$d(gu, F(gx_n, gy_n)) \leq d(gu, gF(x_n, y_n)) + d(gF(x_n, y_n), F(gx_n, gy_n)).$$

Taking the limit as $n \rightarrow \infty$ and using (7), the continuity of g , and G -continuity of F , we have that $d(gu, F(u, v)) = 0$, that is, $gu = F(u, v)$. Using a similar idea, we also have that $gv = F(v, u)$. Therefore, $CcFix(F) \neq \emptyset$.

Suppose now that (b) the tripled (X, d, G) with property A . Let $gx = u$ and $gy = v$ for some $x, y \in X$. Then we have (gx_n, gx) and $(gy_n, gy) \in E(G)$ for each $n \in \mathbb{N}$. By (1) we have

$$\begin{aligned} &\psi(d(gx, F(x, y)) + d(gy, F(y, x))) \\ &\leq \psi(d(gx, gx_{n+1}) + d(gx_{n+1}, F(x, y)) + d(gy, gy_{n+1}) + d(gy_{n+1}, F(y, x))) \\ &\leq \psi(d(F(x_n, y_n), F(x, y))) + \psi(d(F(y_n, x_n), F(y, x))) \\ &\quad + \psi(d(gx, gx_{n+1})) + \psi(d(gy, gy_{n+1})) \\ &\leq 2\theta(d(gx_n, gx), d(gy_n, gy))\psi(M(gx_n, gx, gy_n, gy)) \\ &\quad + \psi(d(gx, gx_{n+1})) + \psi(d(gy, gy_{n+1})). \end{aligned}$$

Letting $n \rightarrow \infty$, we have $\psi(d(gx, F(x, y)) + d(gy, F(y, x))) = 0$. By properties of ψ , we can see that $d(gx, F(x, y)) + d(gy, F(y, x)) = 0$. Finally, $gx = F(x, y)$ and $gy = F(y, x)$. \square

We denote by $\text{CmFix}(F)$ the set of all common fixed points of mappings $F : X^2 \rightarrow X$ and $g : X \rightarrow X$, that is,

$$\text{CmFix}(F) = \{(x, y) \in X^2 : F(x, y) = gx = x \text{ and } F(y, x) = gy = y\}.$$

Theorem 2.6 *In addition to hypotheses of Theorem 2.5, assume that*

(vi) *for any two elements $(x, y), (u, v) \in X \times X$, there exists $(a, b) \in X \times X$ such that*

$$(gx, ga), (gu, ga), (gy, gb), (gv, gb) \in E(G).$$

Then, $\text{CmFix}(F) \neq \emptyset$ if and only if $(X^2)_g^F \neq \emptyset$.

Proof Theorem 2.5 implies that there exists $(x, y) \in X \times X$ such that $gx = F(x, y)$ and $gy = F(y, x)$. Suppose that there exists another $(u, v) \in X \times X$ such that $gu = F(u, v)$ and $gv = F(v, u)$. We will show that $gx = gu$ and $gy = gv$.

By condition (vi) there exists $(a, b) \in X \times X$ such that $(gx, ga), (gu, ga), (gy, gb), (gv, gb) \in E(G)$. Set $a_0 = a, b_0 = b, x_0 = x, y_0 = y, u_0 = u$, and $v_0 = v$. By Lemma 2.4(i) we have sequences $\{a_n\}, \{b_n\}, \{x_n\}, \{y_n\}, \{u_n\}$, and $\{v_n\}$ in X for which

$$\begin{aligned} ga_n &= F(a_{n-1}, b_{n-1}) \quad \text{and} \quad gb_n = F(b_{n-1}, a_{n-1}), \\ gx_n &= F(x_{n-1}, y_{n-1}) \quad \text{and} \quad gy_n = F(y_{n-1}, x_{n-1}), \\ gu_n &= F(u_{n-1}, v_{n-1}) \quad \text{and} \quad gv_n = F(v_{n-1}, u_{n-1}) \end{aligned}$$

for $n \in \mathbb{N}$. By the properties of coincidence points, $x_n = x, y_n = y$ and $u_n = u, v_n = v$, that is,

$$gx_n = F(x, y), \quad gy_n = F(y, x) \quad \text{and} \quad gu_n = F(u, v), \quad gv_n = F(v, u) \quad \text{for all } n \in \mathbb{N}.$$

Since $(gx, ga), (gy, gb) \in E(G)$, we have (gx, ga_0) and $(gy, gb_0) \in E(G)$. Because F and g are G -edge preserving, we have $(F(x, y), F(a_0, b_0)) = (gx, ga_1)$ and $(F(y, x), F(b_0, a_0)) = (gy, gb_1) \in E(G)$. Similarly, (gx, ga_n) and $(gy, gb_n) \in E(G)$. By Lemma 2.4(ii) we obtain

$$\lim_{n \rightarrow \infty} d_n = \lim_{n \rightarrow \infty} M(gx, ga_n, gy, gb_n) = 0,$$

and then

$$\lim_{n \rightarrow \infty} d(gx, ga_n) = 0 \text{ and } \lim_{n \rightarrow \infty} d(gy, gb_n) = 0.$$

Similarly, from $(gu, ga), (gv, gb) \in E(G)$ we have

$$\lim_{n \rightarrow \infty} d(gu, ga_n) = 0 \text{ and } \lim_{n \rightarrow \infty} d(gv, gb_n) = 0.$$

By the triangle inequality we have

$$d(gx, gu) \leq d(gx, ga_n) + d(ga_n, gu) \text{ and } d(gy, gv) \leq d(gy, gb_n) + d(gb_n, gv)$$

for all $n \in \mathbb{N}$. Letting $n \rightarrow \infty$ in these two inequalities, we get that $d(gx, gu) = 0$ and $d(gy, gv) = 0$. Therefore, we have $gx = gu$ and $gy = gv$.

The proof of the existence and uniqueness of a common fixed point can be derived using a similar argument as in Theorem 3.7 in [1]. □

Remark 2.1 In the case where (X, d, \preceq) is a partially ordered complete metric space, letting $E(G) = \{(x, y) \in X \times X : x \preceq y\}$ and $\psi(t) = t$, we obtain Theorem 3.1 and Theorem 3.7 in [1].

3 Applications

In this section, we apply our theorem to the existence theorem for a solution of the following integral system:

$$\begin{aligned} x(t) &= \int_0^T f(t, s, x(s), y(s)) ds + h(t), \\ y(t) &= \int_0^T f(t, s, y(s), x(s)) ds + h(t), \end{aligned} \tag{8}$$

where $t \in [0, T]$ with $T > 0$.

Let $X := C([0, T], \mathbb{R}^n)$ with $\|x\| = \max_{t \in [0, T]} |x(t)|$, for $x \in C([0, T], \mathbb{R}^n)$.

We define the graph G with partial order relation by

$$x, y \in X, \quad x \leq y \iff x(t) \leq y(t) \text{ for any } t \in [0, T].$$

Thus, $(X, \|\cdot\|)$ is a complete metric space endowed with a directed graph G .

Let $E(G) = \{(x, y) \in X \times X : x \leq y\}$. Then $E(G)$ satisfies the transitivity property, and $(X, \|\cdot\|, G)$ has property A.

Theorem 3.1 Consider system (8). Suppose that

- (i) $f : [0, T] \times [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $h : [0, T] \rightarrow \mathbb{R}^n$ are continuous;
- (ii) for all $x, y, u, v \in \mathbb{R}^n$ with $x \leq u, y \leq v$, we have $f(t, s, x, y) \leq f(t, s, u, v)$ for all $t, s \in [0, T]$;
- (iii) there exist $0 \leq k < 1$ and $T > 0$ such that

$$|f(t, s, x, y) - f(t, s, u, v)| \leq \frac{k}{T} (|x - u| + |y - v|)$$

for all $t, s \in [0, T], x, y, u, v \in \mathbb{R}^n, x \leq u, y \leq v$;

(iv) there exists $(x_0, y_0) \in X \times X$ such that

$$x_0(t) \leq \int_0^T f(t, s, x_0(s), y_0(s)) ds + h(t) \quad \text{and}$$

$$y_0(t) \leq \int_0^T f(t, s, y_0(s), x_0(s)) ds + h(t),$$

where $t \in [0, T]$.

Then there exists at least one solution of the integral system (8).

Proof Let $F : X \times X \rightarrow X$, $(x, y) \mapsto F(x, y)$, where

$$F(x, y)(t) = \int_0^T f(t, s, x(s), y(s)) ds + h(t), \quad t \in [0, T],$$

and define $g : X \rightarrow X$ by $gx(t) = \frac{x(t)}{2}$.

System (8) can be written as

$$x = F(x, y) \quad \text{and} \quad y = F(y, x).$$

Let $x, y, u, v \in X$ be such that $gx \leq gu$ and $gy \leq gv$. We have $x \leq u, y \leq v$ and

$$F(x, y)(t) = \int_0^T f(t, s, x(s), y(s)) ds + h(t)$$

$$\leq \int_0^T f(t, s, u(s), v(s)) ds + h(t) = F(u, v)(t) \quad \text{for all } t \in [0, T]$$

and

$$F(y, x)(t) = \int_0^T f(t, s, y(s), x(s)) ds + h(t)$$

$$\leq \int_0^T f(t, s, v(s), u(s)) ds + h(t) = F(v, u)(t) \quad \text{for all } t \in [0, T].$$

Thus, F and g are G -edge preserving.

By condition (iv) it follows that $(X^2)_g^F = \{(x, y) \in X \times X : gx \leq F(x, y) \text{ and } gy \leq F(y, x)\} \neq \emptyset$.

On the other hand,

$$|F(x, y)(t) - F(u, v)(t)|$$

$$\leq \int_0^T |f(t, s, x(s), y(s)) - f(t, s, u(s), v(s))| ds$$

$$= \int_0^T |f(t, s, x(s), y(s)) - f(t, s, u(s), v(s))| ds$$

$$\leq \frac{k}{T} \int_0^T (|x(s) - u(s)| + |y(s) - v(s)|) ds$$

$$\leq k \left(\frac{\|gx - gu\| + \|gy - gv\|}{2} \right)$$

$$\leq kM(gx, gu, gy, gv) \quad \text{for all } t \in [0, T].$$

Then, there exist $\psi(t) = t$ and $\theta \in \Theta$, where $\theta(s, t) = k$ for $s, t \in [0, \infty)$ with $k \in [0, 1)$, such that

$$\psi(\|F(x, y) - F(u, v)\|) \leq \theta(\|gx - gu\|, \|gy - gv\|)\psi(M(gx, gu, gy, gv)),$$

where $M(gx, gu, gy, gv) = \max\{\|gx - gu\|, \|gy - gv\|\}$. Hence, F and g are a θ - ψ -contraction.

Thus, there exists a coupled common fixed point $(x^*, y^*) \in X \times X$ of the mapping F and g , which is the solution of the integral system (8). □

Theorem 3.2 *Consider system (8). Suppose that*

- (i) $f : [0, T] \times [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ and $h : [0, T] \rightarrow \mathbb{R}^n$ are continuous;
- (ii) for all $x, y, u, v \in \mathbb{R}^n$ with $x \leq u, y \leq v$, we have $f(t, s, x, y) \leq f(t, s, u, v)$ for all $t, s \in [0, T]$;
- (iii) for all $t, s \in [0, T], x, y, u, v \in \mathbb{R}^n, x \leq u, y \leq v$,

$$|f(t, s, x, y) - f(t, s, u, v)| \leq \frac{1}{T} \ln(1 + \max\{|x - u|, |y - v|\});$$

- (iv) there exists $(x_0, y_0) \in X \times X$ such that

$$\begin{aligned} x_0(t) &\leq \int_0^T f(t, s, x_0(s), y_0(s)) ds + h(t), \\ y_0(t) &\leq \int_0^T f(t, s, y_0(s), x_0(s)) ds + h(t), \end{aligned}$$

where $t \in [0, T]$.

Then there exists at least one solution of the integral system (8).

Proof Let $F : X \times X \rightarrow X, (x, y) \mapsto F(x, y)$, where

$$F(x, y)(t) = \int_0^T f(t, s, x(s), y(s)) ds + h(t), \quad t \in [0, T],$$

and define $g : X \rightarrow X$ by $gx(t) = x(t)$. As in Theorem 3.1, we have that F and g are G -edge preserving.

By condition (iv) it follows that $(X^2)_g^F = \{(x, y) \in X \times X : gx \leq F(x, y) \text{ and } gy \leq F(y, x)\} \neq \emptyset$.

On the other hand,

$$\begin{aligned} &|F(x, y)(t) - F(u, v)(t)| \\ &\leq \int_0^T |f(t, s, x(s), y(s)) - f(t, s, u(s), v(s))| ds \\ &= \int_0^T |f(t, s, x(s), y(s)) - f(t, s, u(s), v(s))| ds \\ &\leq \frac{1}{T} \int_0^T \ln(1 + \max\{|x(s) - u(s)|, |y(s) - v(s)|\}) ds \\ &\leq \ln\left(1 + \max\left\{\max_{t \in [0, T]} |x(t) - u(t)|, \max_{t \in [0, T]} |y(t) - v(t)|\right\}\right) \end{aligned}$$

$$\begin{aligned} &\leq \ln(1 + \max\{\|x - u\|, \|y - v\|\}) \\ &= \ln(1 + M(gx, gu, gy, gv)) \quad \text{for all } t \in [0, T], \end{aligned}$$

where $M(gx, gu, gy, gv) = \max\{\|gx - gu\|, \|gy - gv\|\}$, which yields

$$\begin{aligned} &\ln(|F(x, y)(t) - F(u, v)(t)| + 1) \\ &\leq \ln(\ln(1 + M(gx, gu, gy, gv)) + 1) \\ &= \frac{\ln(\ln(1 + M(gx, gu, gy, gv)) + 1)}{\ln(1 + M(gx, gu, gy, gv))} \ln(1 + M(gx, gu, gy, gv)). \end{aligned}$$

Hence, there exist $\psi(x) = \ln(x + 1)$ and $\theta \in \Theta$ defined by

$$\theta(s, t) = \begin{cases} \frac{\ln(\ln(1 + \max\{s, t\}))}{\ln(1 + \max\{s, t\})}, & s > 0 \text{ or } t > 0, \\ r \in [0, 1), & s = 0, t = 0, \end{cases}$$

such that

$$\begin{aligned} \psi(d(F(x, y), F(u, v))) &= \psi(\|F(x, y) - F(u, v)\|) \\ &\leq \theta(d(gx, gu), d(gy, gv)) \psi(M(gx, gu, gy, gv)). \end{aligned}$$

Hence, we see that F and g are a θ - ψ -contraction. Thus, there exists a coupled common fixed point $(x^*, y^*) \in X \times X$ of the mapping F and g , which is a solution for the integral system (8). □

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

The author read and approved the final manuscript.

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